



## **From Prototype to Standardization**

Five years of LIDAR Anemometry in the Wind Energy Industry

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# Five Years of Lidar Anemometry in the Wind Energy Industry - From Prototype to IEC standard

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Risø DTU

National Laboratory for Sustainable Energy

$$\Delta \epsilon^b \Theta^{\sqrt{17}} + \Omega \int \delta e^{i\pi} =$$

$$2818284 f(x+\Delta x) = \sum_{i=0}^{\infty} \frac{(\Delta x)^i}{i!} f^{(i)}(x) \int_a^{\infty} \chi^2 \sum_{i=0}^{\infty} \frac{(\Delta x)^i}{i!} f^{(i)}(x) = \{2.71828\}$$

# Outline

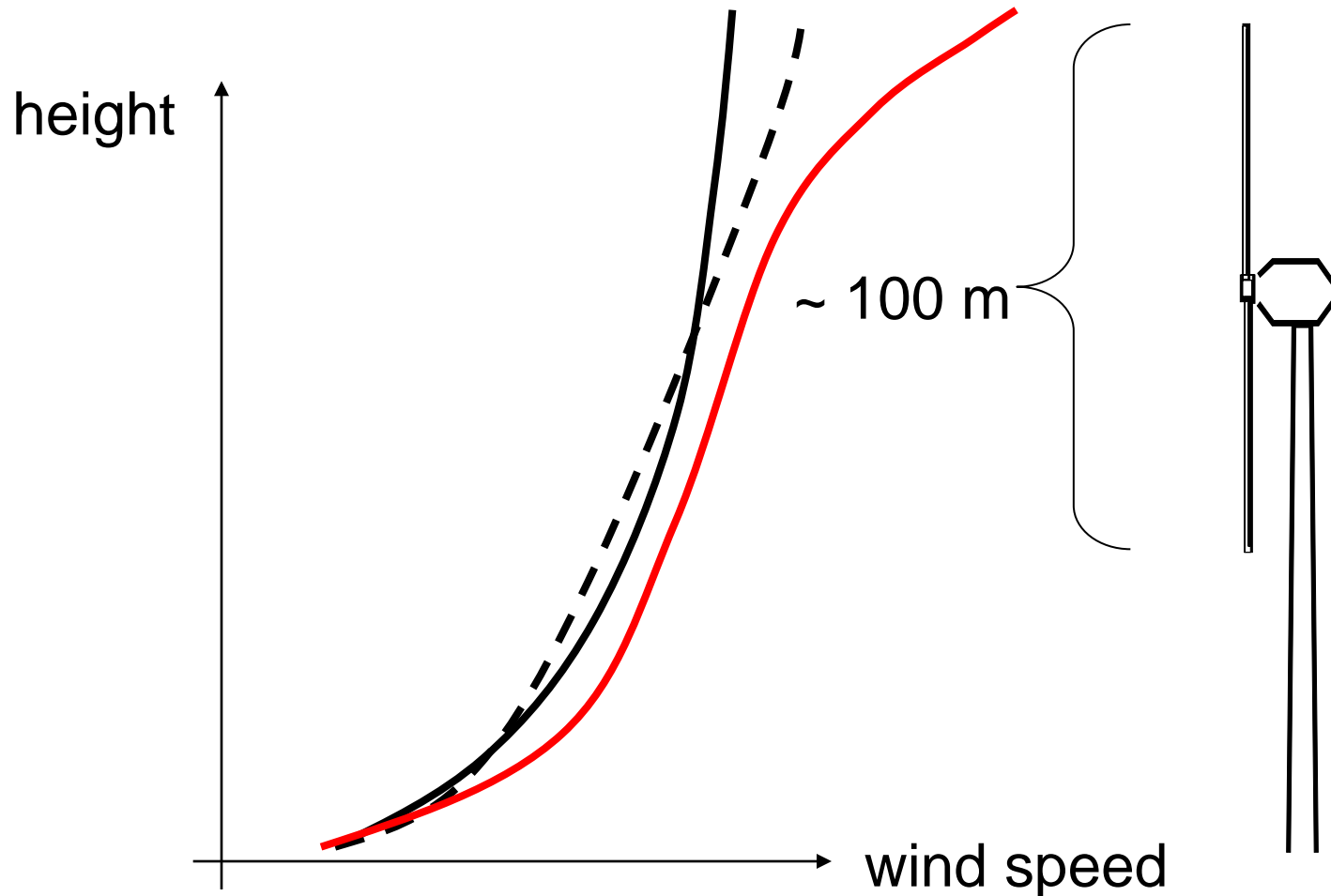
- **Wind Measurements in Wind Energy**
- Commercially available systems
- The market
- State of the art
- Challenges

# Wind in Wind Energy

- 10 minute average horizontal wind speed,  $U$
  - 10 minute average wind direction
  - Turbulence (STDEV in 10 min at 10 Hz)
  - Flow angles
  - 50 year wind
- 
- For a few months to +1 year
  - Offshore, forests, ridges etc
  - High availability (>90%)

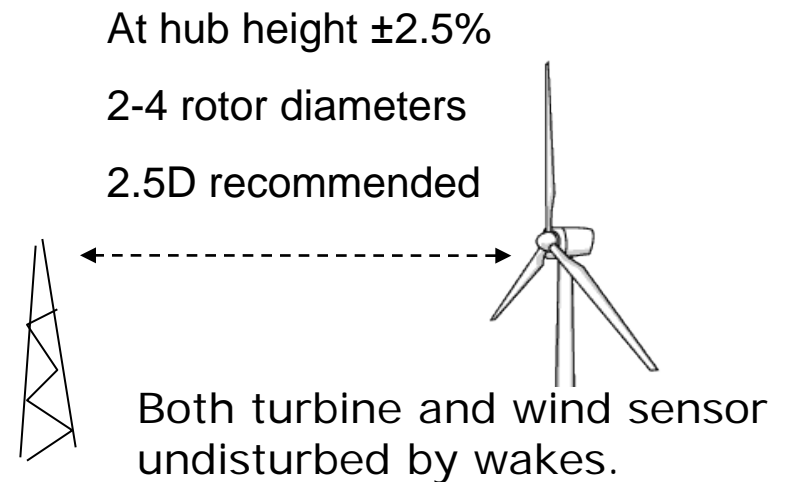
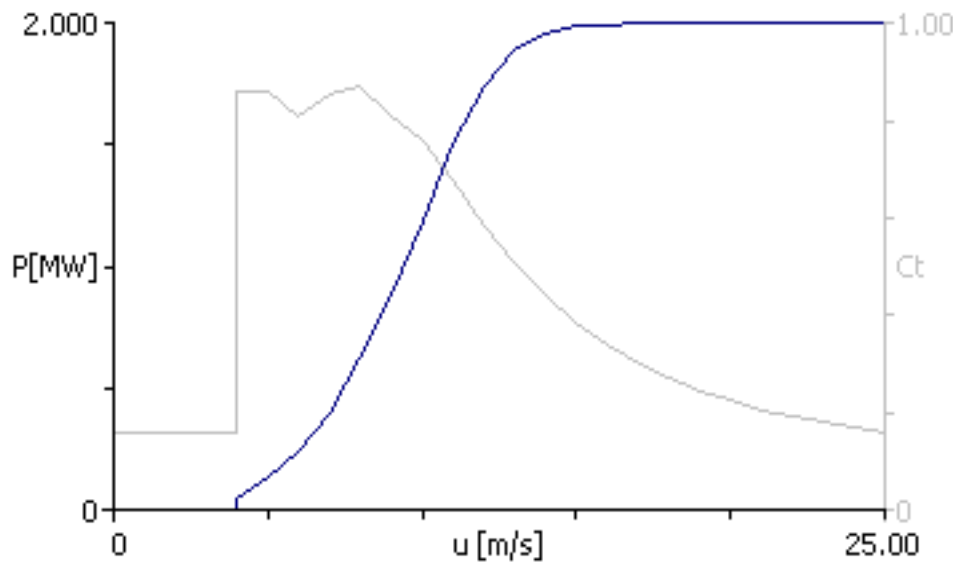
# Wind in Wind Energy

- Today at hub height,  $\sim 60\text{-}110\text{ m}$
- Future over rotor area i.e. from  $40$  to  $200\text{ m}$ .



# Power Performance

- Measurement of the 10 minute averaged power as a function of the 10 minute wind.



Simplified : Power =  $C \cdot (\text{wind speed})^3$

In practice : 1% in m/s  $\rightarrow$  0 – 3% in  $W \rightarrow$  0 – 3% error in predicted money

# Power Performance

## When

R&D, turbine optimisation

Turbine specification (comparison between brands, prediction of production)

Acceptance tests once built

+ 180 h for completed test. Free sectors + ~ 4 to 16 m/s wind speeds.

→ 1-2 months in practice.

A lot of money available at this stage, penalties are high for failed acceptance tests

## Demand on sensor

Cup anemometer better than class 1.7 A

Standard uncertainty :  $< 0.05 \text{ m/s} + 0.005 \cdot U$

Calibration before and after

Wind vane,  $\pm 5^\circ$  in wind direction

$\pm 2.5\%$  from hub height



# Power Performance

## Lidar anemometer opportunities

1 Realistic measurement to tip of blade

### **More repeatable power performance tests**

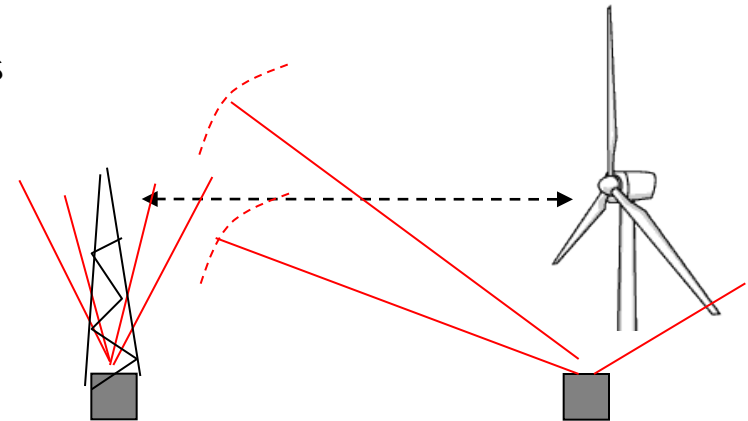
IEC standard 61400-12-1 under revision

- Screening of atypical shear and veer
- Normalisation for power law shear, i.e.  $U_{eq}$
- Stand alone lidar.

2 Redeployable sensor

### **More turbines tested**

- In big farms sometimes only 5% of the turbines are tested.



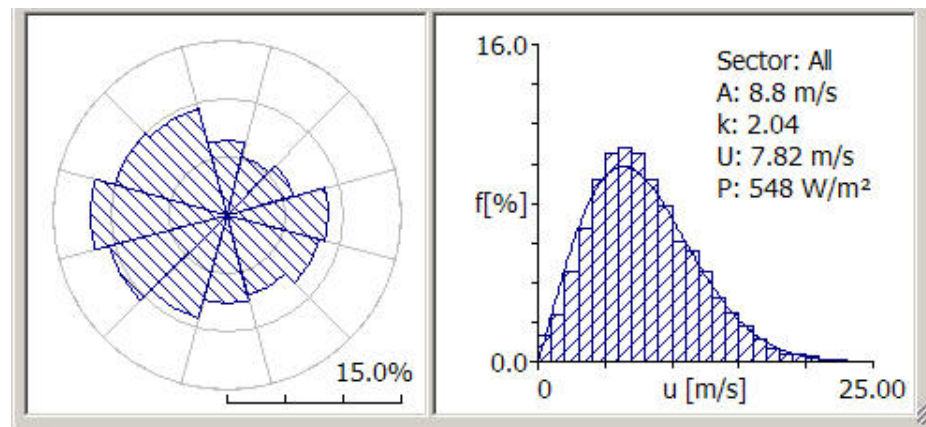
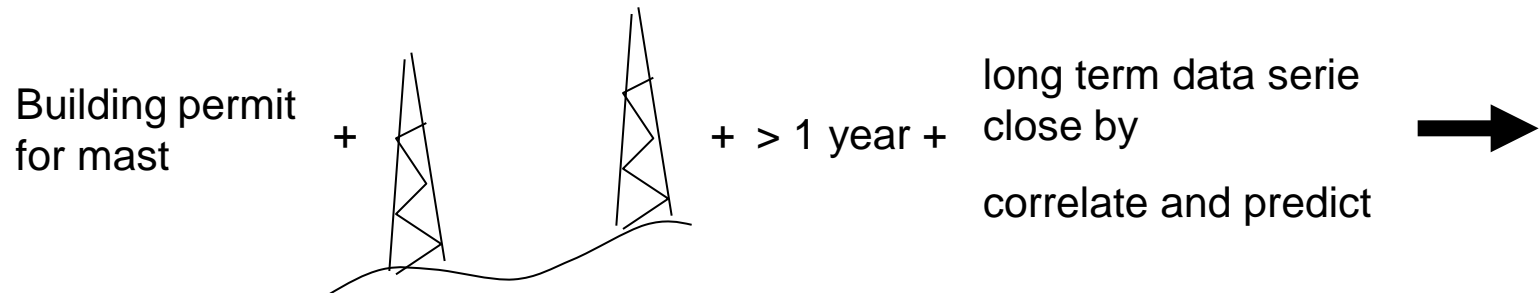
## Challenges

- Accuracy, less than  $\pm 0.1$  m/s in offset and  $\pm 1\%$ , for stand alone option
- $\pm 1\%$  of hub height vs sample volume FWHM 20 m
- Low standard deviation
- Traceability
- All beams in free wind (narrow cone angles?)



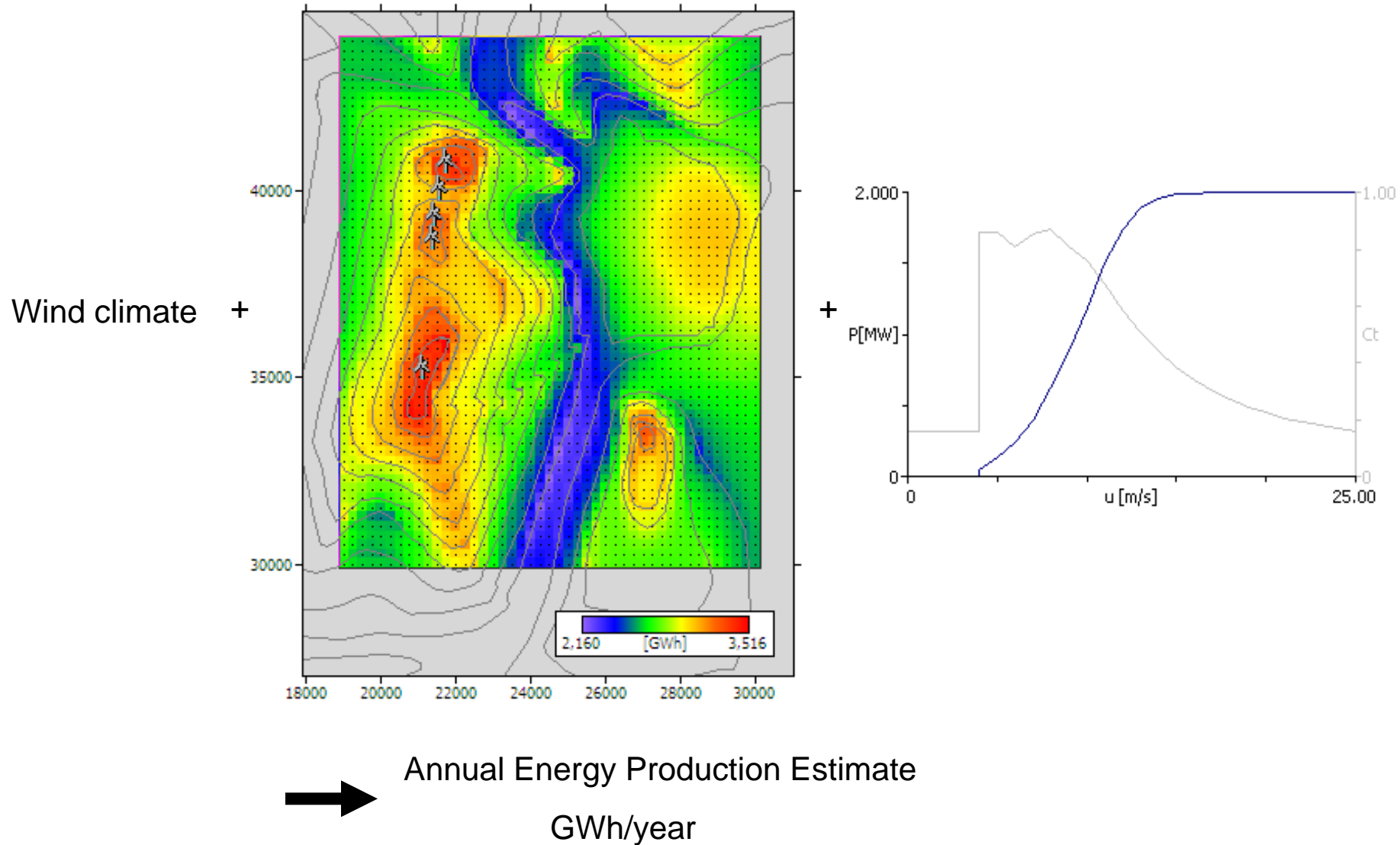
# Wind Resource Assessment

- To obtain building permits and bank loans

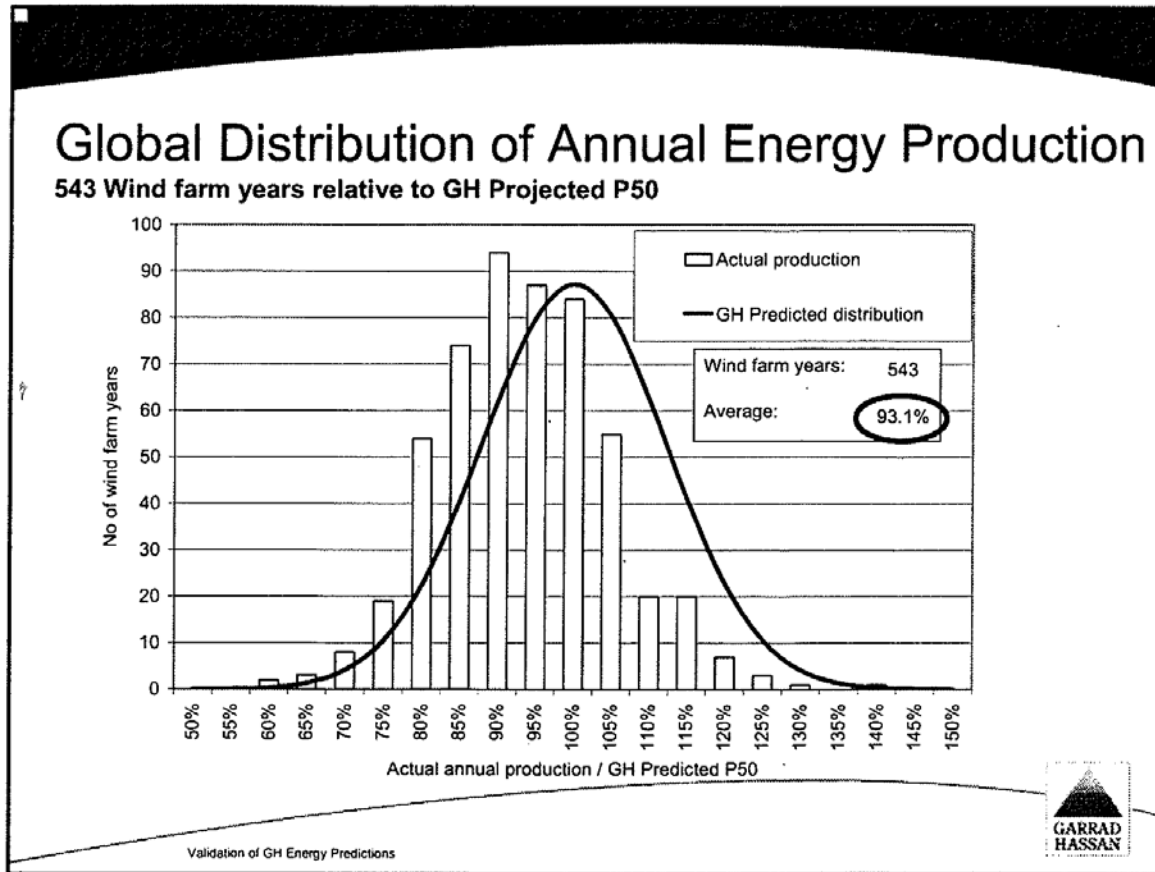


Fitted Weibull distribution  
and wind direction rose

# Wind Resource Assessment



# Wind Resource Assessment



European wind resource map with a 3% margin.

The cost, including measurement campaigns between 2009 and 2015, estimated to 175M€

US (113 years) 90%

US 2007 (40 years) 89%

Under performance or over estimation ?

Not due to 3% sensor error

# Wind Resource Assessment

No standard but "bankability"

€ 15 000 in consultancy cost per 2 MW turbine

1MW rated power costs 1.5M€

## Opportunities

1 No building permits

**Faster start, longer measurement series**

2 Always at hub height

**Reduce bias and STDEV in AEP estimates**

3 Shear and veer data over rotor plane (in future standard ?)

**Less uncertainty in investment**

4 Redeployable sensor

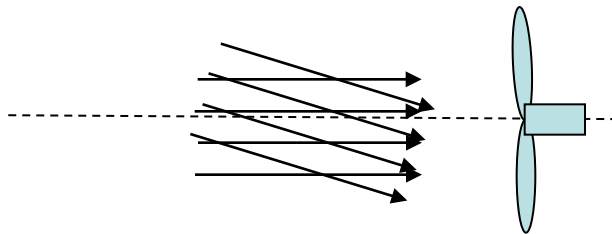
**Verification of flow models**

## Challenges

- Really a need in flat terrain
- Reliability (+ 1 year measurements)
- Traceable accuracy
- Availability (> 90%, not correlated with wind speed)

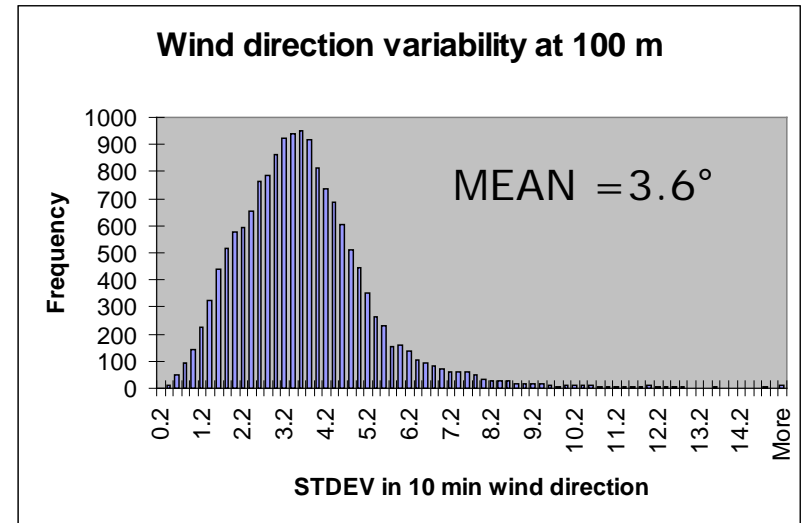
# Turbine control – Yaw

- Optimised power when the turbine faces the wind



Yaw error :  $\text{Power} * \cos^2(\theta)$

## Wind direction variability in a flat site



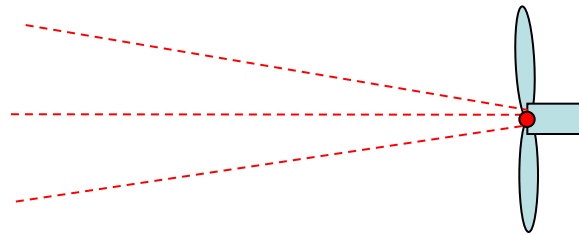
Wind direction measured on turbine.

Turbine yaws a few times every 10 min to keep aligned with wind direction.

Forecasts of wind direction can help the control routines.

Catch the wind : "10% more power"  
 Risø : "1-2 % more power"

# Turbine control – Anti Yaw LIDAR



## Anti Yaw Lidar

- Few hundred meters upwind
- Accuracy better than 3 degrees

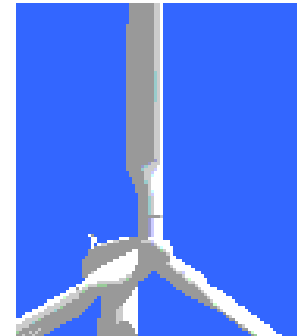
## Challenge

How to avoid to misinterpretate turbulence?

# Turbine control – pitch and flaps

## Pitch control:

- Collective pitch
- Individual pitch
- Reduce loads 20-30%
- Improve power production
- Similar to the anti yaw lidar but also above and below hub



## Flaps:

- Reduce loads
- Improve power production

## Flap input

- Angle of attack
- > 2 sensors per wing
- 5 m ahead

# Outline

- Wind measurements in Wind Energy
- **Commercially available systems**
- The market
- State of the art
- Challenges
- Conclusions



# Zephir – Natural Power Consultants

- Continuous Wave
- Variable focus setting
- VAD Scan 50 points, rotating wedge
- 60° elevation angle
- Cloud correction algorithm
- CE marked – eyesafe IEC 60825-1

- 1.56  $\mu\text{m}$  fiber laser
- 1 W output power
- 7 cm diameter lens
- No offset on LO
- RIN and not head or tail wind
- One LOS every 20 ms
- Frequency resolution 200 kHz

- Measures to 200 m in good conditions
- Minimum range 10 m
- 5 heights sequentially
- 3 sec per height, 1 sec to change
- about 30 measurements at one height in 10 min
- € 125.000



# WindCube – Léosphere

- Range gated
- Fixed focus at  $\sim 100$  m
- 4 directions,  $90^\circ$  start-stop wedge
- $60^\circ$  elevation angle
- eyesafe IEC 60825-1

- Measures to 200 m in good conditions
- Minimum range 40 m
- 10 heights in parallel
- 4 sec per full revolution
- about 600 measurements in 10 min (125 completely uncorrelated)
- € 150.000

- $1.54 \mu\text{m}$
- 200 ns pulse
- $10 \mu\text{J}$
- 20 kHz
- 500 ms to get one LOS velocity
- 10000 averages per LOS
- 5 cm diameter lens
- Offset on LO
- Frequency resolution 5 MHz

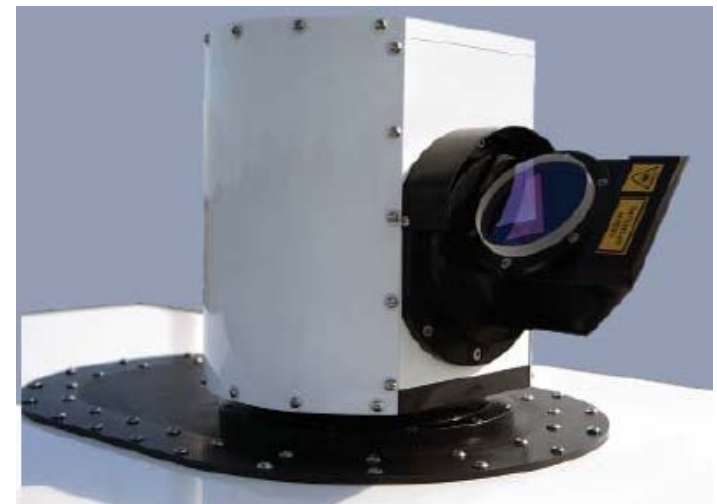


# Galion – Sgurr Energy

- Range gated
- Collimated
- two axis scanner head
- eyesafe IEC 60825-1
- 9 month warranty

- Measures to 200 m in good conditions
- 20 sec per full revolution
- 30 uncorrelated meas in 10 min (in 4 direction mode)
- + 30 vertical meas
- € 150.000

- 1.54  $\mu\text{m}$
- 180 ns pulse
- 10  $\mu\text{J}$
- 20 kHz
- 50 mm aperture
- Offset on LO



# Vindicator – Catch The Wind

- Range gated
- Three telescopes
- No moving parts
- Turbine mounted

- Measures to 300 m in good conditions
- Aim price \$125.000

- 200 ns pulse



# Competing technologies

## Towers

Tilt up tower: 1 week assembly    € 16.000 + 500 per sensor    max 70 m

100 m tower: < €150.000 (Offshore, -3)    3 months for permit + construction

## SODAR

3 \* Cheaper :                      \$ 40.000                      (Lidar € 100.000 -150.000)

5 \* Less accurate :               $\sigma \sim 0.5$  m/s              (Windcube  $\sigma < 0.1$  m/s)

beam bending and low availability at high wind speed

0.1 \* power consumption : 10 W                      (LIDAR > 100 W)

= 1.5



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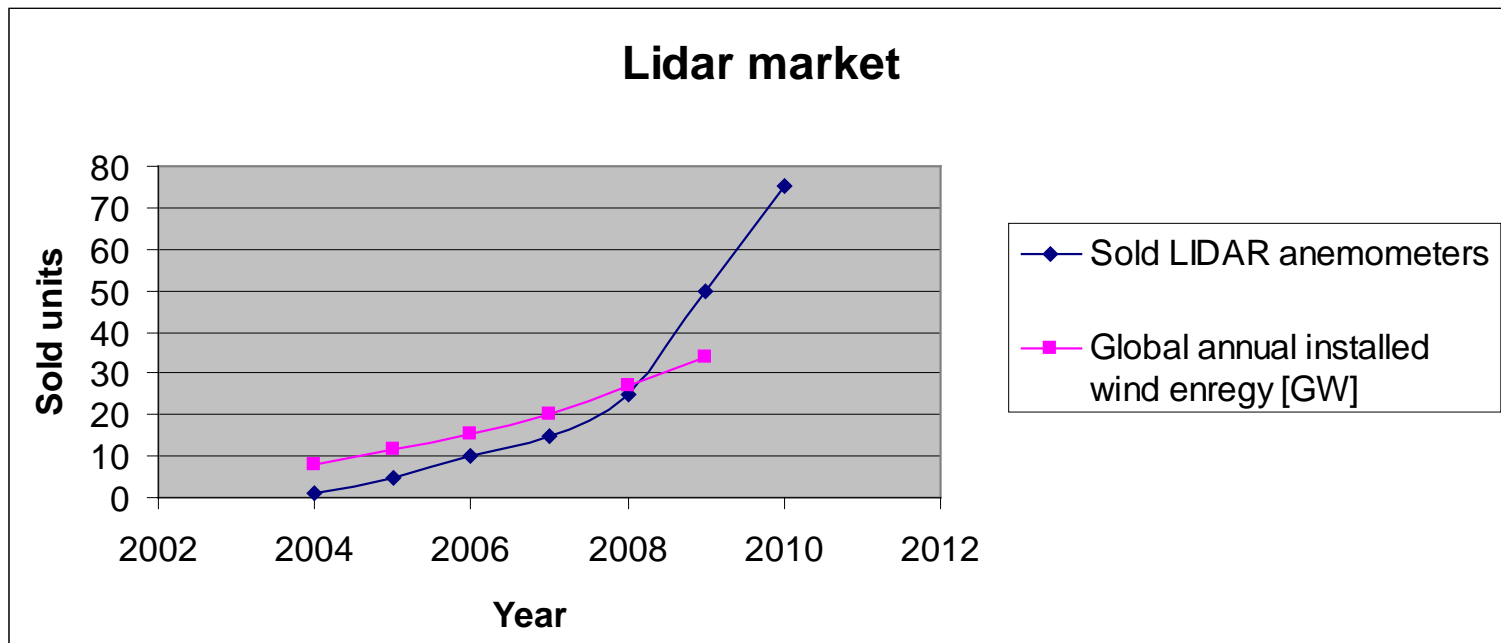
# Lidar market

Estimated cumulative sold lidars:

Zephir ~ 60 systems sold

WindCube ~ 50 systems

Vindicator and Galion < 10 systems



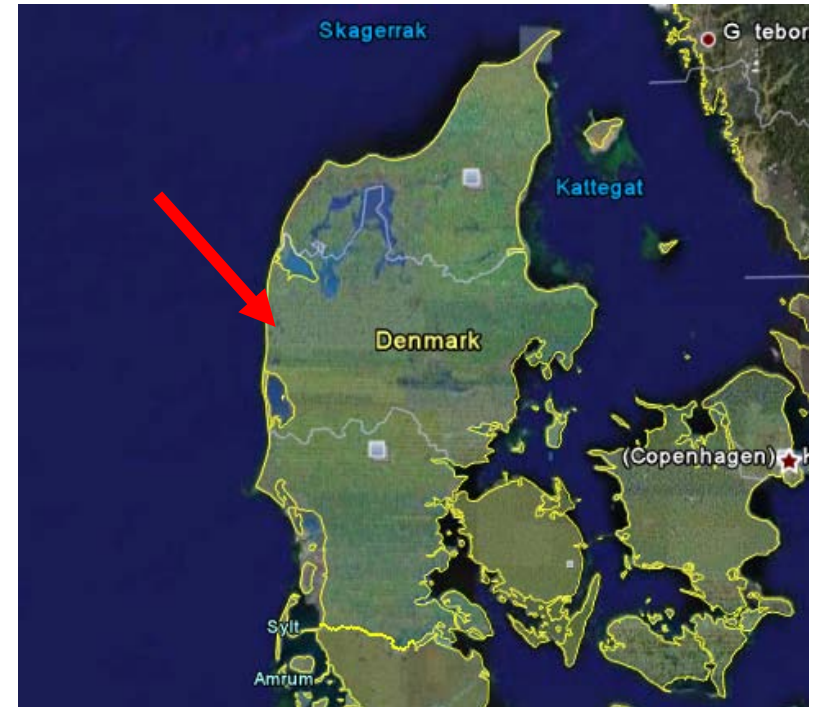
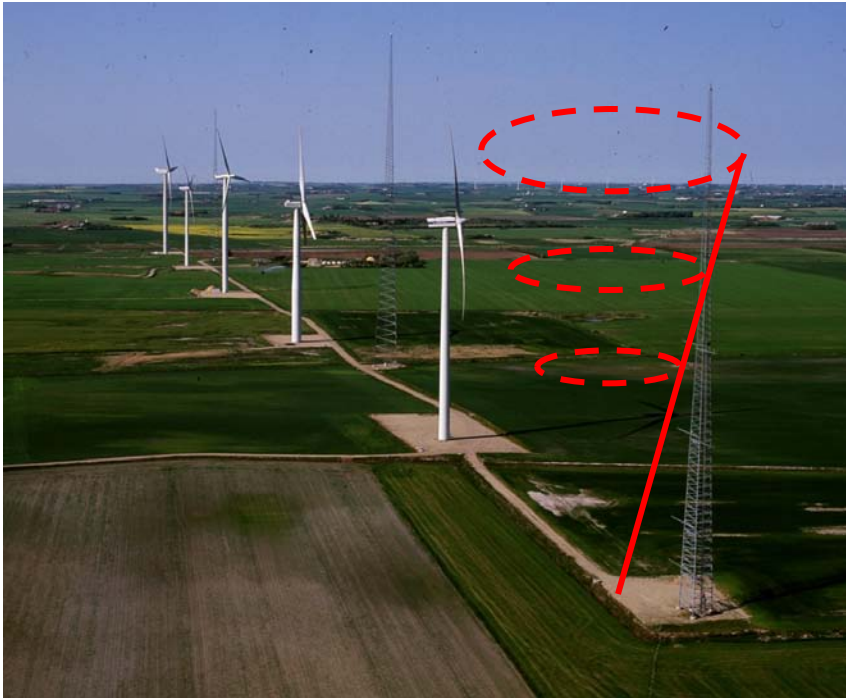
2010 : 75 LIDAR = 10 M€

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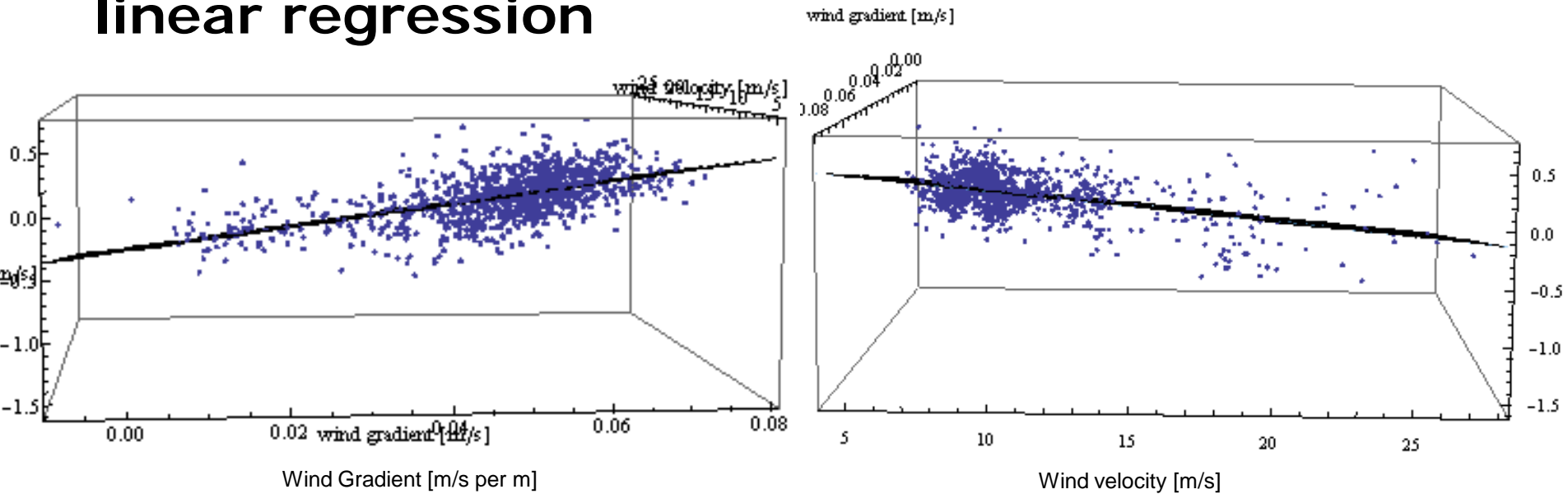
# Testing of LIDAR anemometers in Høvsøre



## Høvsøre Large Wind Turbin Test Facility

- West coast of Denmark, flat terrain, wide range of horizontally homogeneous wind speed.
- Site equipped with rain and cloud sensors
- **15** Zephirs, **15** Windcubes and **1** Gallion tested = 31 lidars
- **90** months of comparison with class 1 cup anemometers @ 40-116 m (160 m)
- Data from 2 other flat sites evaluated

# Error vs Velocity and Shear: 2-parametric linear regression



$$\Delta U = 0.163133 + 7.94365 \tilde{x} + 0.0248088 y$$

$$R^2 = 0.33406$$

where

$\Delta U$  is lidar - cup [m/s]

$x$  is wind shear [m/s per m]

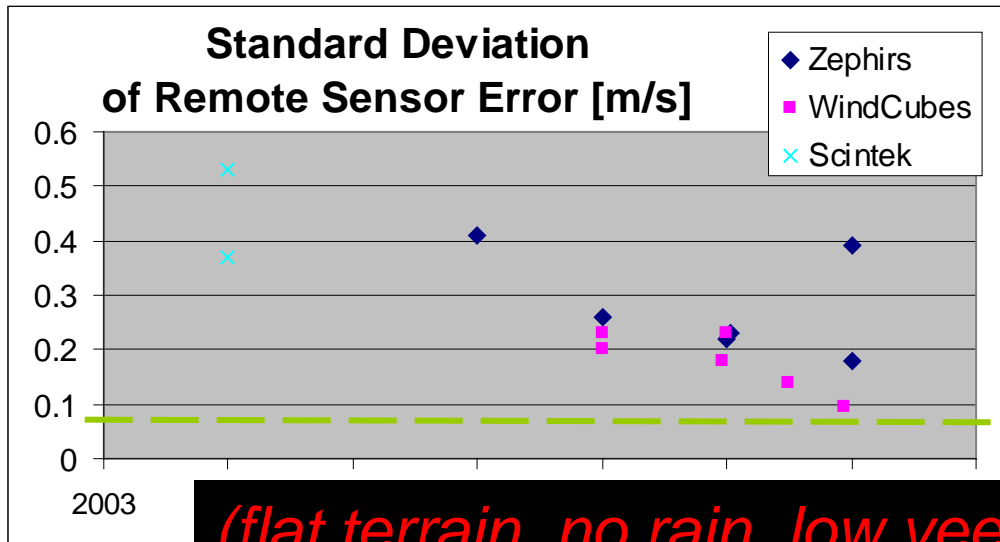
$y$  is wind speed [m/s]

**Estimate**

**7.9 m above intended height**

**- 2.48 % mostly due to cone angle**

# Development of Lidar anemometry



**2006: Zephir commercial model introduced. Hardware issues.**

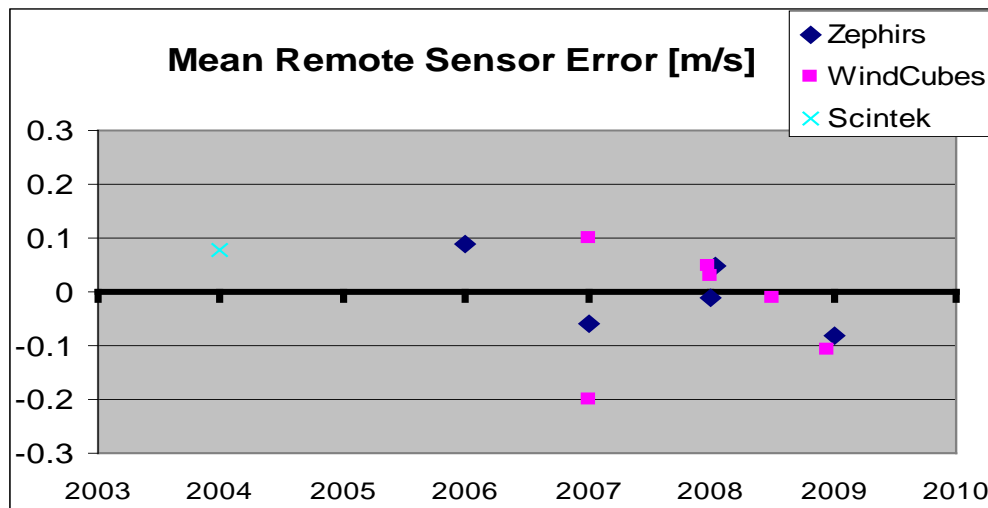
**2007: Ceilometer installed, screening on clouds: positive bias and  $\sigma$  reduced, availability drops. Leosphere introduces Windcube.**

**2008: Cloud correction: availability increases. Cone angle accuracy: bias reduced.**

**2008.5: Estimator improved: nonlinear problems solved.**

**2009: Improved test conditions, lower RIN. Improved test conditions.**

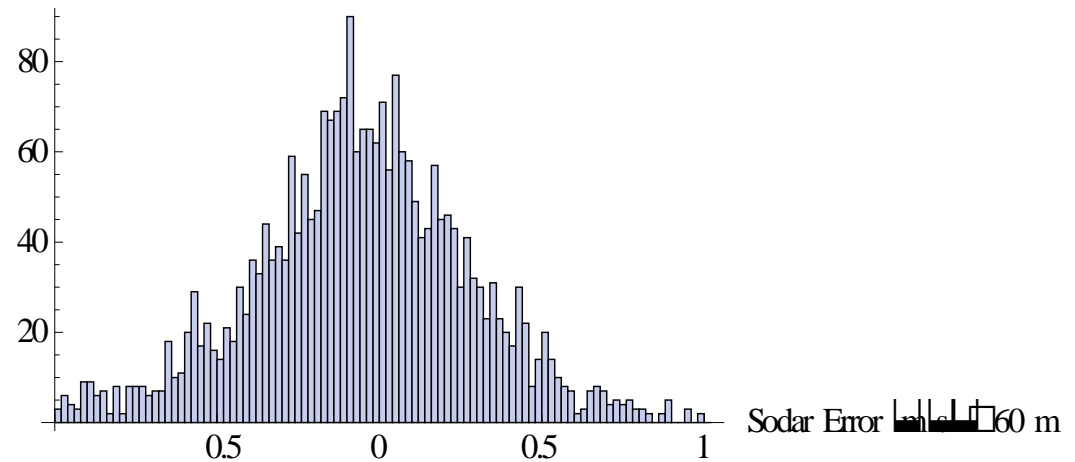
**Vindicator and Galion commercial**



# Histograms of Remote sensor – cup

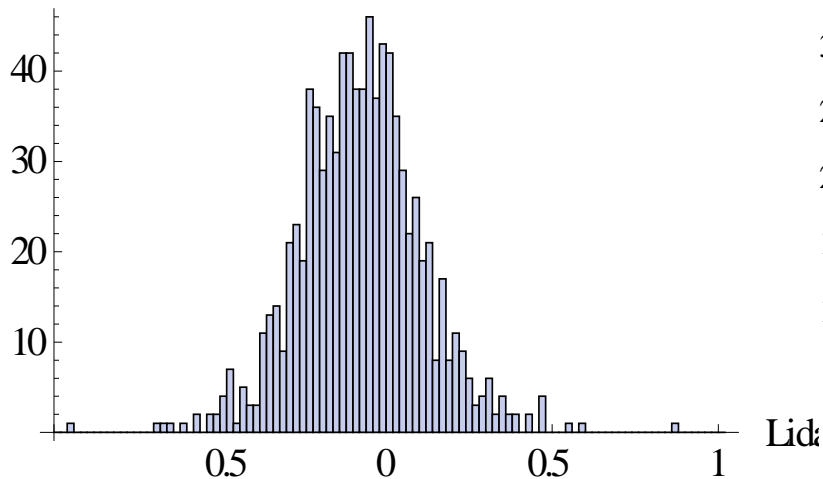
at 60 m

Scintek 2004



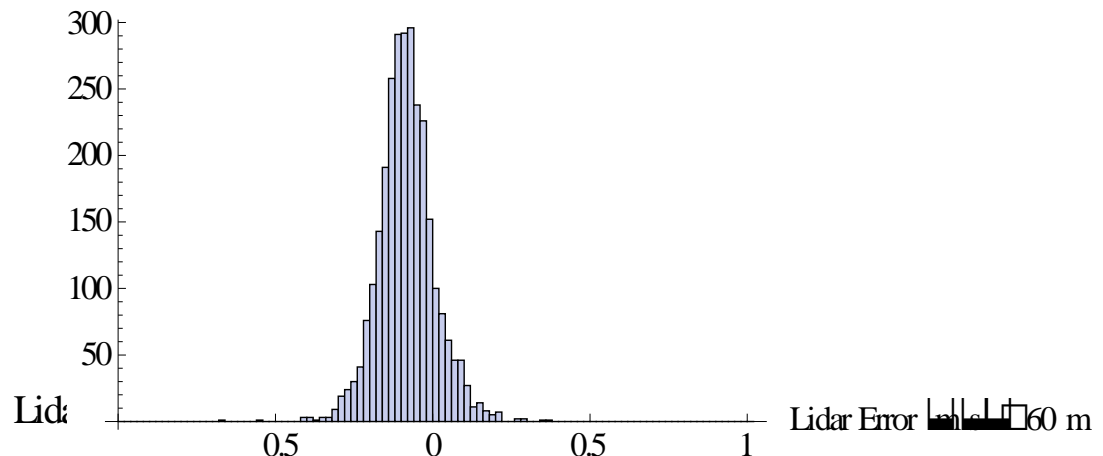
Scintek mean -0.08, STDEV: 0.37

Zephir



Zephir mean -0.08, STDEV: 0.18

Windcube



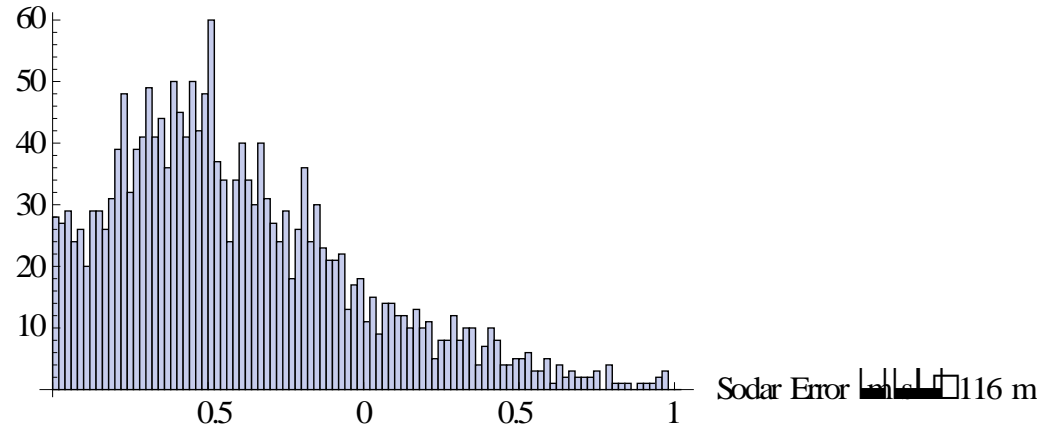
WC mean -0.08, STDEV: 0.09

# Histograms of Remote sensor – cup

at 116 m

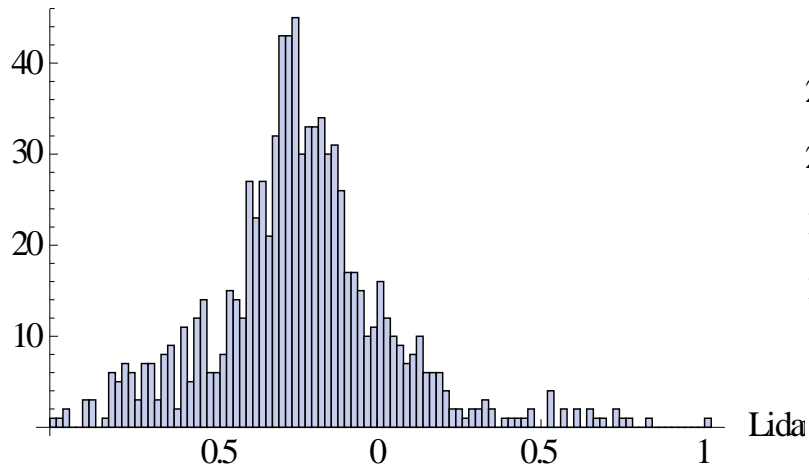
Scintek

At the coast of  
northern Denmark,  
>90% availability



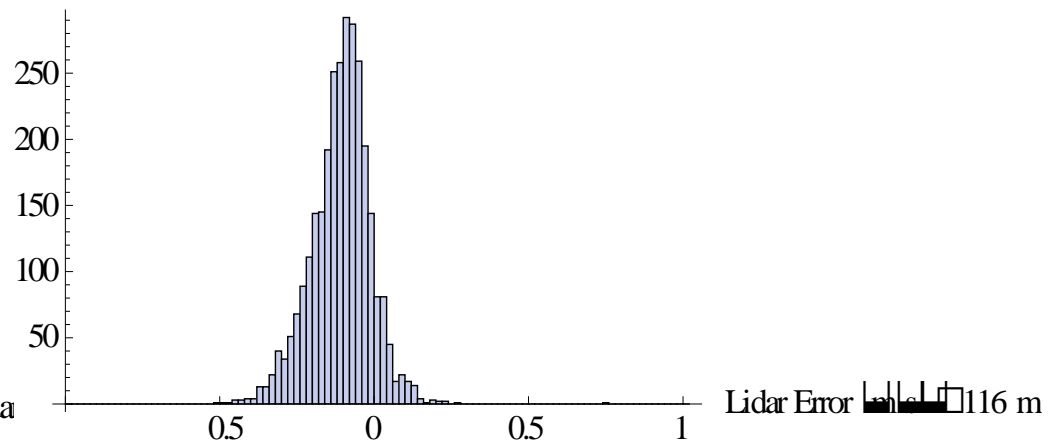
Scintek mean -0.55, STDEV: 0.53

Zephir



Zephir mean -0.29, STDEV: 0.39

Windcube

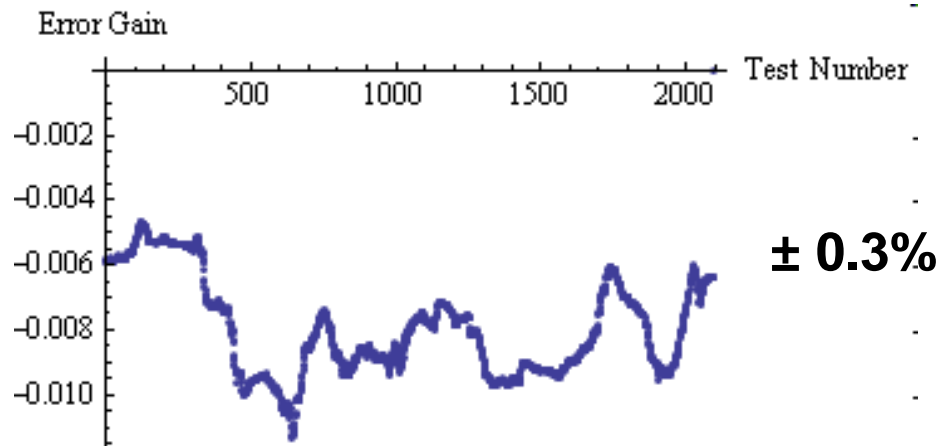
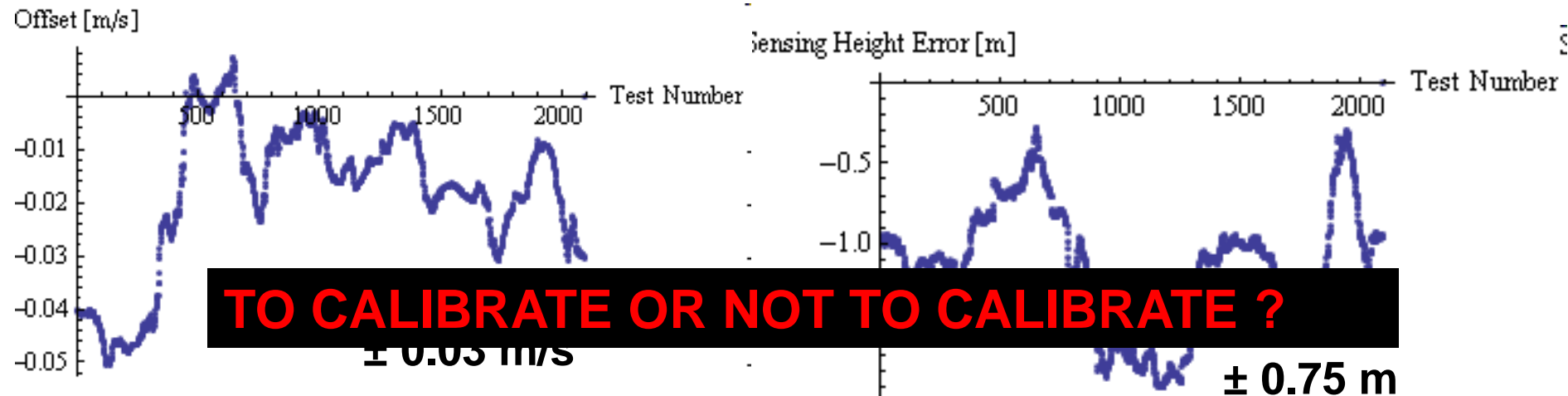


WC mean -0.11, STDEV: 0.10

# A good measure of Lidar anemometry accuracy

Estimation of errors for sliding time period

1000 test parameters @ 100 m



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# Challenges

Traceable Accuracy

Best units probably there (flat terrain, no rain, low veer, moderate  $\sigma$ )

Price

/3

Reliability

\*3 , i.e. much more reliable

Complex terrain

3 LOS in same space = 3 Lidars with good scanners

Power consumption, roughly 100 W (unheated)

Selfsupporting for a year



# Conclusions

- A need for more and better wind measurements in the wind energy industry
- Need to have in the near term
  - More repeatable Power Performance, new IEC standard will include lidar anemometry
  - Ressource assessment, at hub heighth with lidar beats lower masts, bankable at a few occasions
  - Turbine control, research stage
- 4 commercial suppliers, 10M€ in 2010.
- 0.1 m/s stdev traceable accuracy (Flat terrain, no rain, little veer, moderate turbulence)
- Still key challenges to be met (complex terrain)

Thank you

$$\begin{aligned} & \Delta \int_0^b \Theta^{\sqrt{17}} + \Omega \int \delta e^{i\pi} = \\ & \sum_{i=0}^{\infty} \frac{(\Delta x)^i}{i!} f^{(i)}(x) = \sum_{i=0}^{\infty} \frac{(\Delta x)^i}{i!} f^{(i)}(x) = \{2.71828\} \end{aligned}$$